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multi-joint robot with two tools and interpolation

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Multi-joint robot and control device thereof - Patent 20050204848

1 in this way, a handling system by the **robot** having **two tools** at a single unit ... a position and an attitude of the **tool** such as linear **interpolation**. ...

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Robot bus architecture with distributed electronics - Patent 5130631

In a **multi-joint robot** having at least **two** joints dispersed away from a central processor as described above requires decomposition, or **interpolation**, ...

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Method of controlling robot movements - US Patent 5157315

Method for positioning a **tool** of a **multi-joint robot** Issued on: January 16, ... reading orientation values at initial and terminal **interpolation** points; ...

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Method of controlling articulated robot - US Patent 5187418

Method for positioning a **tool** of a **multi-joint robot** ... The first control point is controlled by way of **interpolation**, and the second control point is ...

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2.1 Summary. The **robot** adopts a **multijoint** structure, and the key parts of it are. **two** plane arms, each of which consists of a forearm and an upper ...

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the human arm to interact with the **robot** in **two** modes: (1) passive (P) and N. Hogan,

The mechanics of **multi-joint** posture and movement control, Biol. ...

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introduction of innovative **tools** for advanced production planning. purposes. Advanced **multi-joint robot** Jystem for the production of complex ...

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criteria and **multi-joint** stability criteria separately. (a)For. single joint motion experiment with a **two**-armed space **robot**", Proc. IEEE ...
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In this method, a polynomial based on Hermite cubic **interpolation** is applied to Yano F, Tooda Y. Preferable movement of a **multi-joint robot** arm using ...
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